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Application No.: 10/537,962  
Art Unit 2617Attorney Docket No. 3673-0198PUS1  
Reply to Office Action dated February 5, 2008  
Page 2**Amendments to the Claims**

1. (Previously Presented) A mobile telephone apparatus comprising:

- a storage unit in which key information is stored;
- a reception unit for receiving an emergency signal including key information;
- a control unit for determining whether the key information stored in the storage unit and the key information included in the emergency signal match; and
- a transmission unit for transmitting a rescue signal, wherein

when the key information stored in the storage unit and the key information included in the emergency signal match, a rescue signal is transmitted from the transmission unit.

2. (Previously Presented) The mobile telephone apparatus according to Claim 1, wherein the storage unit stores individual-identifying information for identifying the user of the mobile telephone apparatus, and wherein the individual-identifying information is included in the rescue signal.

3. (Currently Amended) The mobile telephone apparatus according to Claim 1, further comprising another control unit for controlling speaking function, a switch, and a battery, wherein the switch is configured to switch on and off the power supply from the battery to the ~~other control unit~~ for controlling speaking functions, and the battery supplies power to the control unit that determines whether the key information stored in the storage unit and the key information included in the emergency signal match, irrespective of the switch status.

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4. (Previously Presented) The mobile telephone apparatus according to Claim 1, wherein when the key information stored in the storage unit and the key information included in the emergency signal match, a wave is transmitted together with the rescue signal.

5. (Previously Presented) The mobile telephone apparatus according to Claim 1, wherein when the key information stored in the storage unit and the key information included in the emergency signal match, light is generated.

6. (Previously Presented) A rescue system provided with a mobile telephone apparatus and a portable detector, wherein

the mobile telephone apparatus comprises: a storage unit in which key information is stored; a reception unit for receiving an emergency signal including key information; a control unit for determining whether the key information stored in the storage unit and the key information included in the emergency signal match; and a transmission unit for transmitting a rescue signal, wherein when the key information stored in the storage unit and the key information included in the emergency signal match, the transmission unit transmits a rescue signal; and

the portable detector receives the rescue signal transmitted from the mobile telephone apparatus.

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7. (Previously Presented) A rescue system provided with a mobile telephone apparatus, three or more reception units installed in a disaster site, and a computer, wherein

the mobile telephone apparatus comprises: a storage unit in which key information is stored; a reception unit for receiving an emergency signal including key information; a control unit for determining whether the key information stored in the storage unit and the key information included in the emergency signal match; and a transmission unit for transmitting a rescue signal, wherein when the key information stored in the storage unit and the key information included in the emergency signal match, the transmission unit transmits a rescue signal;

the reception unit receives the rescue signal transmitted from the mobile telephone apparatus; and

the computer locates the position of the mobile telephone apparatus on the principle of trilateration.

8. (Currently Amended) A rescue system provided with a mobile telephone apparatus and a robot, wherein comprising:

a ~~the~~ mobile telephone apparatus ~~comprises~~ having a storage unit in which key information is stored; a reception unit for receiving an emergency signal including key information; a control unit for determining whether the key information stored in the storage unit and the key information included in the emergency signal match; and a transmission unit for transmitting a rescue signal, wherein when the key information stored in the storage unit and the

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key information included in the emergency signal match, the transmission unit transmits a rescue signal; and

a the robot for moving moves close to the mobile telephone apparatus while receiving the rescue signal transmitted from the mobile telephone apparatus.

9. (Currently Amended) The rescue system according to Claim 8, wherein

the mobile telephone apparatus ~~is configured~~ has means to generate a sound wave together with the rescue signal when the key information stored in the storage unit and the key information included in the emergency signal match; and

~~the robot performs the reception of the rescue signal and the reception of the sound wave;~~  
and wherein the distance between the robot and the mobile telephone apparatus is calculated by determined based on the a time lag between the reception of the rescue signal and the reception of the sound wave by the robot.

10. (Currently Amended) The rescue system according to Claim 9, wherein the robot ~~can~~ includes means for correcting the velocity of sound on the basis of environment parameters.

11. (New) A method of rescuing a person whose exact location is uncertain, comprising:

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transmitting an emergency rescue signal containing key information not open to the public by a rescuer toward a location where the person to be rescued may be located;

using a portable telephone of the person to be rescued to receive the emergency rescue signal and compare the key information in the received signal with information stored in the telephone to determine if the signal is an emergency signal;

transmitting a rescue signal from the mobile telephone of the person to be rescued;

detecting the rescue signal;

determining the location of the mobile telephone of the person to be rescued; and

committing a robot toward the determined location.